

Path Integrals and semiclassical Propagator

Path Integral for single particle QM:

Propagator $K = \langle x_N | e^{-iHt} | x_0 \rangle$

$$= \langle x_N | e^{-i \int_0^t \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right] dt} | x_0 \rangle$$

$\hat{p}$ and $\hat{x}$ don't commute $\rightarrow$ Trotterize

$$= \langle x_N | \left[e^{-i \epsilon \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right]} \right]^N | x_0 \rangle$$

$$N \rightarrow \infty$$

$$\epsilon \rightarrow 0 \text{ s.t.}$$

$$N\epsilon = t$$

$$= \langle x_N | e^{-i \epsilon \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right]} | x_{N-1} \rangle$$

$$\langle x_{N-1} | e^{-i \epsilon \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right]} | x_{N-2} \rangle$$

$$\vdots$$

$$\langle x_1 | e^{-i \epsilon \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right]} | x_0 \rangle$$

Now

$$\langle x_{j+1} | e^{-i \epsilon \left[\frac{\hat{p}^2}{2m} + V(\hat{x}) \right]} | x_j \rangle = \int dp \langle x_{j+1} | e^{-i \epsilon \frac{p^2}{2m}} | p \rangle$$

$$\times \langle p | e^{-i \epsilon V(\hat{x})} | x_j \rangle$$

$$= \int dp e^{-i \epsilon \frac{p^2}{2m}} e^{-i \epsilon V(x)} e^{i p (x_{j+1} - x_j)}$$

$$= \sqrt{\frac{m}{2\pi i \epsilon}} \exp \left[i m \frac{(x_{j+1} - x_j)^2}{2\epsilon} - i \epsilon V(x_j) \right]$$

$$\Rightarrow K(x_N, x_0, t)$$

$$= \lim_{\substack{N \rightarrow \infty \\ N\varepsilon = t}} \left[\frac{m}{2\pi i\varepsilon} \right]^{N/2} \int dx_1 \dots dx_{N-1} \exp \left[i\varepsilon \left(\sum_{j=0}^{N-1} \frac{m(\dot{x}_{j+1} - \dot{x}_j)^2}{2\varepsilon^2} - V(x_j) \right) \right]$$

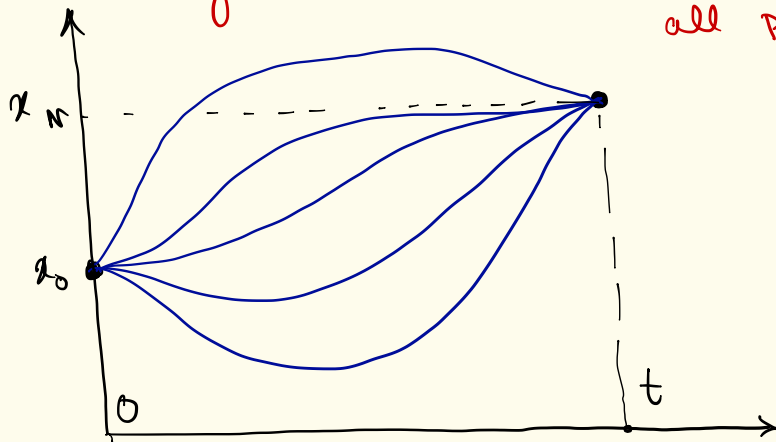
$$\sim \int Dx(t) \exp i \int_0^t dt \left[\frac{m \dot{x}^2}{2} - V(x) \right]$$

"Functional Integral"

$$= \int Dx(t) \exp \left[i \int h(x, \dot{x}) dt \right]$$

with $x(t=0) = x_0$ and $x(t) = x_N$.

Pictorially: sum of $\exp(i \text{ action})$ over all paths.



Above, we didn't make any approximation.
Now, let's consider the semiclassical limit
and relate it to Gutzwiller's formula.

To derive the semiclassical propagator, we will make
a stationary phase approximation. As a
warm-up towards it, consider a 1-dimensional
integral:

$$I = \int dx \quad e^{i\phi(x)/a} \quad \text{where 'a' is}$$

a positive number. As $a \rightarrow 0$ the integrand
varies rapidly and the integral is dominated
by those portions of a the integrand,
where integrand varies the least i.e.,

$$\left. \frac{d\phi}{dx} \right|_{x_0} = 0.$$

There may be many (including infinitely
many) solutions to this eqn. and one has
to add contributions from all of them.

Expanding the integrand around one such point

$$\int dx e^{i \varphi(x)/a} = \exp \left[\frac{i}{a} \left[\varphi(x_0) + \frac{(x-x_0)^2}{2} \varphi''(x_0) + \dots \right] \right]$$

$$= \int d(x-x_0) \exp \left[\frac{i \varphi(x_0)}{a} + \frac{(x-x_0)^2}{2} \varphi''(x_0) + \dots \right]$$

$$= \sqrt{\frac{2\pi i a}{\varphi''(x_0)}} e^{i \varphi(x_0)/a}$$

Let's write the prefactor to the exponential

$$\text{as } \sqrt{\frac{2\pi i a}{\varphi''(x_0)}} = \sqrt{\frac{2\pi i a \operatorname{sign}[\varphi''(x_0)]}{|\varphi''(x_0)|}}$$

$$= e^{i[\pi/4 \operatorname{sign} \varphi''(x_0)]} \sqrt{\frac{2\pi a}{|\varphi''(x_0)|}}.$$

As mentioned above, there may be several saddle points. Denoting various such saddles by an index b .

$$I = \sum_b e^{i 2b\pi/4} \sqrt{\frac{2\pi a}{|\varphi''(x_b)|}} e^{\frac{i \varphi(x_b)}{a}}$$

where $\mathcal{D}_b = \text{sign}(\varphi''(x_b))$.

To consider application to the path integral, we need to study the

Multi-dimensional version:

let $x = (x_1, \dots, x_n)$

$$I_n = \int dx_1 \dots dx_n e^{i\varphi(x)/\hbar} = \int d^n x e^{i\varphi(x)/\hbar}$$

The stationary phase points are $\frac{\partial \varphi}{\partial x_i} = 0$

$\forall i = 1, 2, \dots, n$. Expanding φ to second order around such points,

$$\varphi(x) = \varphi(x_0) + \frac{1}{2} \sum_{i,j} (x_i - x_{i0})(x_j - x_{j0}) \frac{\partial^2 \varphi}{\partial x_i \partial x_j}$$

Thus, the multi-dimensional integral is still

Gaussian:

$$\int d^n x e^{i\varphi(x)/\hbar} = e^{i\varphi(x_0)} \int d^n y \exp \left[\frac{i}{2\hbar} y_i y_j \frac{\partial^2 \varphi}{\partial x_i \partial x_j} \right]_{x_0}$$

where $\vec{y} = \vec{x} - \vec{x}_0$

$$= \int d^n y \quad \exp \quad \frac{i}{2a} [y^T M y]$$

where $M_{ij} = \frac{\partial^2 \phi}{\partial y_i \partial y_j} |_{y_0}$.

Diagonalizing $y^T M y = z^T D z$

where D is a diagonal matrix. The

Jacobian is 1 because $y = R z$ where

R is orthogonal. Thus, $\frac{i}{2a} \sum_k D_k z_k^2$

$$I_n = e^{i\phi(x_0)/a} \int d^n z \quad e^{\frac{i}{2a} \sum_k D_k z_k^2}$$

$$= e^{i\phi(x_0)/a} \prod_k \left[\sqrt{\frac{2\pi a i}{D_k}} \right]$$

$$= e^{i\phi(x_0)/a} (2\pi a)^{n/2} \prod_k \left[i^{\text{sign}(D_k)} \right]^{1/2} \frac{1}{\prod_k \sqrt{|D_k|}}$$

$$= e^{i\phi(x_0)/a} \frac{(2\pi a)^{n/2}}{\sqrt{|\text{Det}(M)|}} e^{i\pi/4}$$

where $\pi = \#$ of positive eigenvalues of M
 $- \#$ of negative " " "

finally, summing over all such saddle points,

$$I_n = \sum_b e^{i 2\pi b \pi / 4} (2\pi a)^{n/2} \left| \det \left(\frac{\partial^2 \Phi}{\partial x_i \partial x_j} \right) \right|^{-1/2} e^{i \Phi(x_b) / a}$$

Application to the Path Integral

$$S(x_0, x_1, \dots, x_n)$$

$$= e^{\sum_{j=0}^{n-1} \left[\frac{m}{2} \left[\frac{x_{j+1} - x_j}{\epsilon} \right]^2 - v(x_j) \right]}$$

$$\frac{\partial^2 S}{\partial x_k \partial x_l} = \frac{m}{\epsilon} \left[2\delta_{kl} - \delta_{k+1,l} - \delta_{k-1,l} - \frac{\epsilon^2}{m} v''(x_k) \delta_{kl} \right]$$

There is a very simple and interesting result:

$$\det \left(\frac{\partial^2 S}{\partial x_k \partial x_l} \right) = - \left[\frac{m}{\epsilon} \right]^n \left[\frac{\partial^2 S}{\partial x_0 \partial x_n} \right]^{-1}$$

Thus the determinant is just proportional to $\frac{\partial^2 \mathcal{L}}{\partial x_0 \partial x_N}$! To determine the overall phase,

we need $\mathcal{N} = \overset{\uparrow \mathcal{N}_+}{\# \text{ of positive eigenvalues of } \frac{\partial^2 \mathcal{L}}{\partial x_k \partial x_l}} - \# \text{ of negative eigenvalues of } \frac{\partial^2 \mathcal{L}}{\partial x_k \partial x_l} \downarrow \mathcal{N}_-$

Recall the expression for the path integral :

$$K(x_N, x_0, t)$$

$$= \lim_{\substack{N \rightarrow \infty \\ N \neq t}} \left[\frac{m}{2\pi i \epsilon} \right]^{N/2} \int dx_1 \dots dx_{N-1} \exp \left[i \epsilon \left(\sum_{j=0}^{N-1} \frac{m(x_{j+1} - x_j)^2}{2\epsilon^2} - V(x_j) \right) \right]$$

Thus, the overall phase is

$$e^{-\frac{i\pi}{4} N} e^{i2\pi/4}$$

$$\mathcal{N}_+ + \mathcal{N}_- = N - 1$$

$$\Rightarrow \mathcal{N} = \mathcal{N}_+ - \mathcal{N}_- = N - 1 - 2\mathcal{N}_-$$

$$\Rightarrow e^{-\frac{i\pi}{4} N + i2\pi/4} = e^{-\frac{i\pi}{4} N} e^{i\frac{\pi}{4} (N - 1 - 2\mathcal{N}_-)}$$

$$= \frac{e^{-i\pi/4}}{e} \frac{e^{-i2-\pi/2}}{e}$$

Thus, we need only keep track of the number of negative eigenvalues of $\frac{\partial^2 S}{\partial x_k \partial x_l}$ along a classical trajectory.

This leads to the Van-Vleck formula:

$$K(x_b, x_0, t) = \sum_b \frac{e^{-i2-\pi/2}}{\sqrt{2\pi i}} \left| \frac{\partial^2 S_b}{\partial x_b \partial x_0} \right|^{1/2} e^{i S_b(x_b, x_0, t)}$$

where the sum is over all classical paths connecting x_b to x_a .

for a d -dimensional problem:

$$K = \sum_b \frac{e^{i\phi - b\pi/2}}{(2\pi i)^{d/2}} \left| \det \frac{\partial^2 S_b}{\partial \vec{x}_N \partial \vec{x}_0} \right| \exp(i S_b)$$

This formula is exact when
 $V(x) = a_0 + a_1 x + a_2 x^2$.

Intuition for Van Vleck's formula

$F(T)$ has a very important physical meaning: $|F|^2$ is the probability density to transition from x_0 to x_N in time t . To determine this probability, consider the fan of classical trajectories from x_0 to x_N with varying velocities at $t=0$. The variation in momenta is given by:

$$\delta p_a = m \delta \dot{x}_0(t=0)$$

$$\text{Since } m \frac{d^2 x}{dt^2} = - \frac{\partial V}{\partial x}$$

$$\Rightarrow m \frac{d^2 \delta x}{dt^2} = - \frac{\partial^2 V}{\partial x^2} \bigg|_{x_c(t)} \delta x$$

The spread of initial momenta determine the spread of x_N at t , the more the spread, the lower the probability.

To determine δx_N , recall,

$$\frac{\partial S}{\partial x_0} = -P_0$$

$$\Rightarrow \frac{\partial^2 S}{\partial x_0 \partial x_N} = -\frac{\partial P_0}{\partial x_N}$$

$$\Rightarrow \delta P_0 = -\delta x_N \frac{\partial^2 S}{\partial x_0 \partial x_N}$$

$$\Rightarrow \delta x_N = -\delta P_0 \underbrace{\left[\frac{\partial^2 S}{\partial x_0 \partial x_N} \right]^{-1}}_{\text{inverse prob. of finding particle at } x_N \text{ after time } t \text{ starting at } x_0}$$

$$\Rightarrow (P(t))^2 \sim \frac{\partial^2 S}{\partial x_0 \partial x_N}$$